

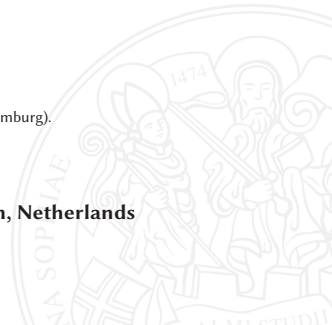
Utility Maximization with Constant Costs

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Germany

Joint work with **Sören Christensen** (University of Hamburg).

8th General AMaMeF Conference, Amsterdam, Netherlands
June 22, 2017



Market Model and Problem Formulation



The Market Model and Transaction Costs

The **financial market** consists of $n + 1$ assets $P = (P^0, P^1, \dots, P^n)$ with prices

$$\begin{aligned}dP(t) &= \text{diag}(P(t)) [\mu(Y(t))dt + \sigma(Y(t))dW(t)], \\dY(t) &= \alpha(Y(t))dt + \beta(Y(t))dW(t).\end{aligned}$$



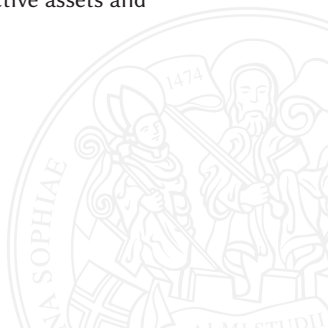
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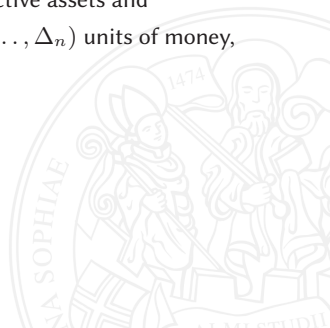
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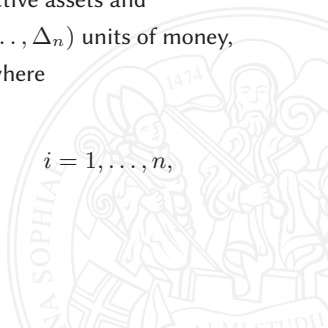
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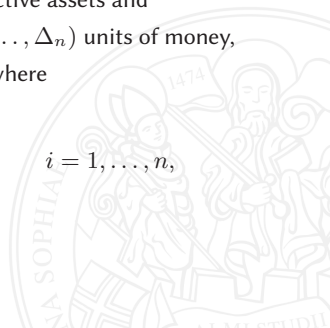
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$$\begin{aligned}\xi_0 &= x_0 - \sum_{i=1}^n [\Delta_i + \gamma_i |\Delta_i| + K_i] 1_{\{\Delta_i \neq 0\}}, \\ \xi_i &= x_i + \Delta_i,\end{aligned}$$

where $\gamma_i \in (0, 1)$ and $K_i > 0$ for $i = 1, \dots, n$.



Solvency and Trading Strategies

A portfolio $x \in \mathbb{R}^{n+1}$ is **solvent** if it has a positive **liquidation value** $L(x)$, i.e.

$$L(x) \triangleq x_0 + \sum_{i=1}^n [x_i - \gamma_i |x_i| - K_i] > 0.$$

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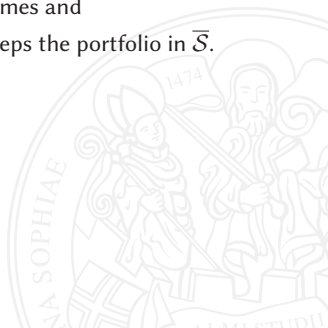
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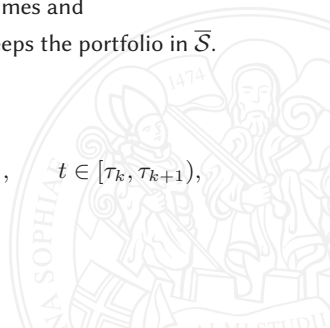
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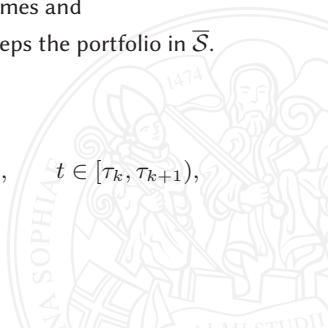
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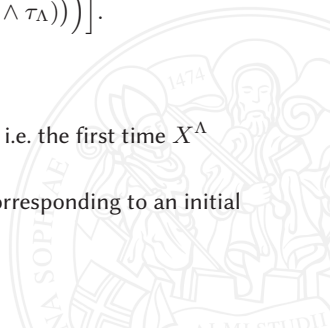
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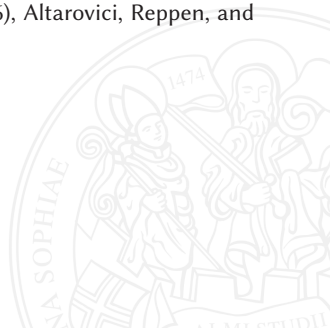
In the above,

- τ_Λ denotes the **bankruptcy time** of the strategy Λ , i.e. the first time X^Λ leaves the solvency region \mathcal{S} , and
- $\mathcal{A}(t, x, y)$ denotes the set of admissible strategies corresponding to an initial state of (t, x, y) .



In the existing literature, there are three different approaches:

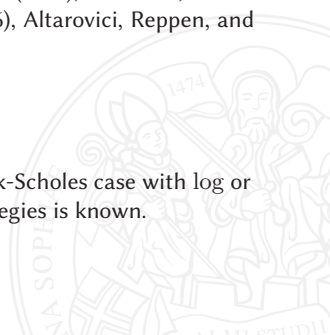
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Note: To the best of our knowledge, not even in the Black-Scholes case with log or power utility, a rigorous existence result for optimal strategies is known.



The Candidate Optimal Strategy



The Quasi-Variational Inequalities

The Bellman principle suggests that \mathcal{V} can be linked to the **quasi-variational inequalities** (QVIs)

$$\min\{-\partial_t \mathcal{V}(t, x, y) - \mathcal{L}\mathcal{V}(t, x, y), \mathcal{V}(t, x, y) - \mathcal{M}\mathcal{V}(t, x, y)\} = 0$$

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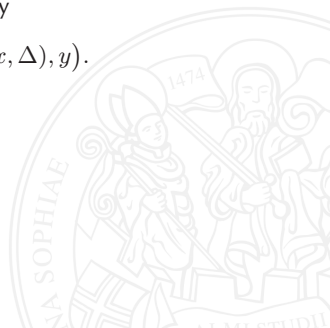
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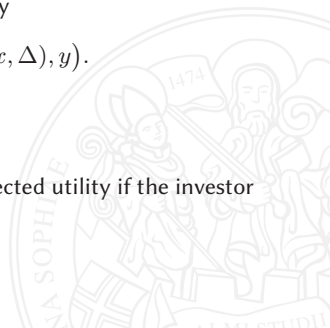
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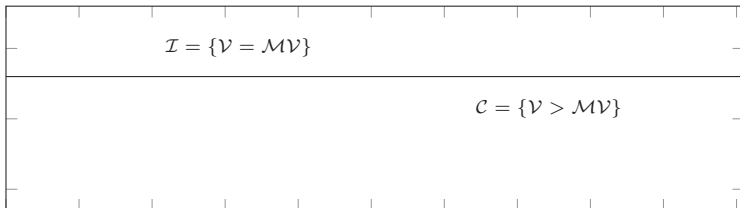
Note: $\mathcal{M}\mathcal{V}(t, x, y)$ can be thought of as the optimal expected utility if the investor is **forced to make a transaction** at time t .



A Candidate Optimal Control

Observe that

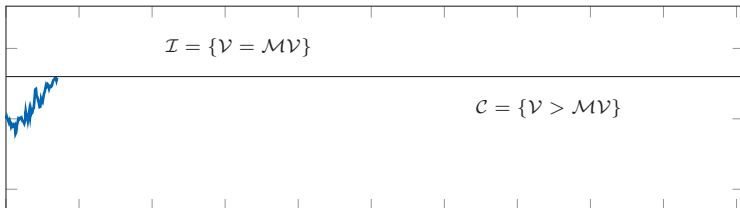
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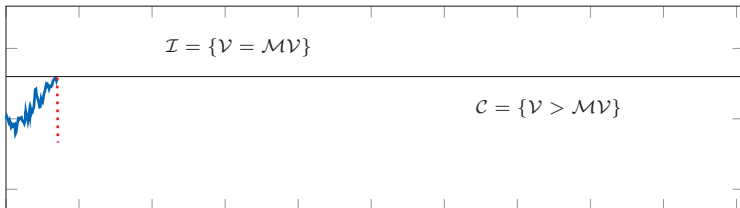
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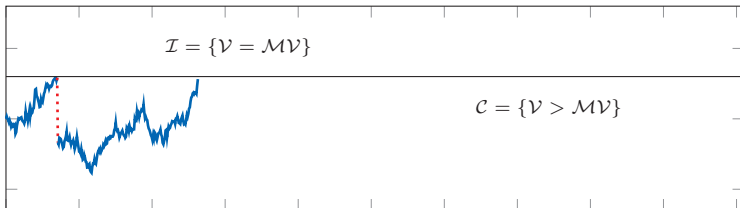
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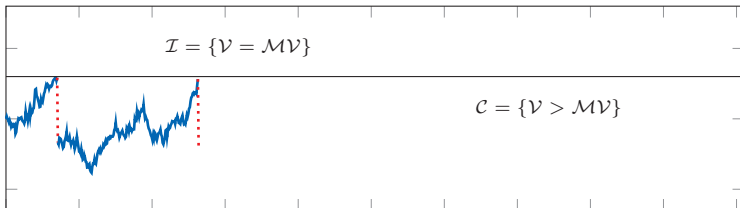
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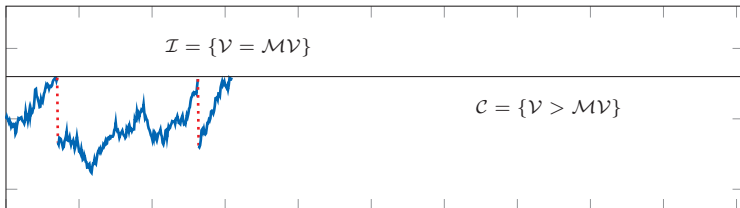
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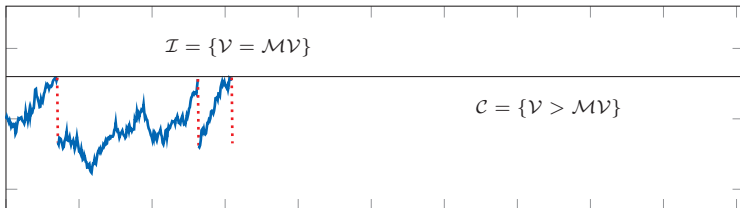
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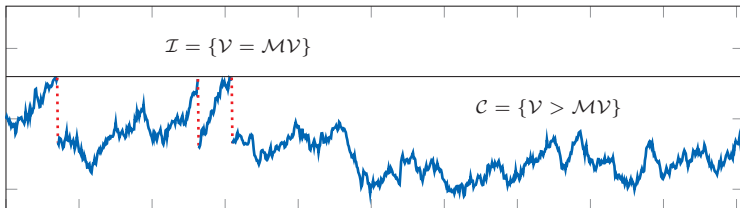
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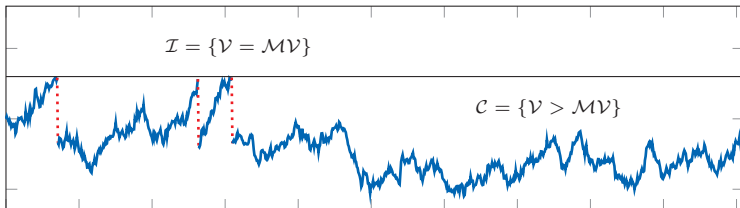
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Problem: To verify optimality we need sufficient regularity to apply Itô's formula, but it seems unlikely that the QVIs admit a $C^{1,2}$ -solution.

Verification via Superharmonic Functions



A Formal Optimal Stopping Problem

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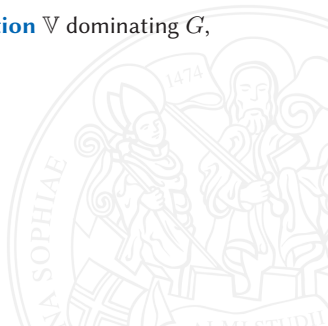
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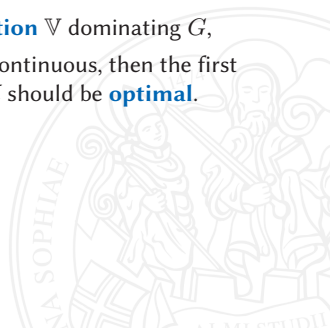
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- \mathcal{V} should equal the **smallest superharmonic function** \mathbb{V} dominating G ,
- if \mathbb{V} is lower semi-continuous and G is upper semi-continuous, then the first hitting time of the set $\{\mathbb{V} = G\} = \{\mathcal{V} = \mathcal{M}\mathcal{V}\} = \mathcal{I}$ should be **optimal**.



A Formal Optimal Stopping Problem

By the **Bellman principle**, we expect that

$$\mathcal{V}(t, x, y) = \sup_{\tau \in \mathcal{T}_t} \mathbb{E}[\mathcal{M}\mathcal{V}(\tau, X(\tau), Y(\tau))] = \sup_{\tau \in \mathcal{T}_t} \mathbb{E}[G(\tau, X(\tau), Y(\tau))],$$

which is nothing but an **optimal stopping problem** with reward $G \triangleq \mathcal{M}\mathcal{V}$.

The general theory of optimal stopping suggests that

- \mathcal{V} should equal the **smallest superharmonic function** \mathbb{V} dominating G ,
- if \mathbb{V} is lower semi-continuous and G is upper semi-continuous, then the first hitting time of the set $\{\mathbb{V} = G\} = \{\mathcal{V} = \mathcal{M}\mathcal{V}\} = \mathcal{I}$ should be **optimal**.

Remark: $G = \mathcal{M}\mathcal{V}$ is upper semi-continuous if $\mathcal{V} = \mathbb{V}$ is upper semi-continuous. That is, to verify optimality, continuity of \mathbb{V} should suffice!

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Moreover, define the **pointwise infimum** $\mathbb{V} = \inf_{h \in \mathbb{H}} h$.



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Verification Theorem (Belak and Christensen (2016))

Suppose that \mathbb{V} is continuous. Then $\mathbb{V} = \mathcal{V}$ and the candidate optimal control Λ^* defined in terms of the sets

$$\mathcal{C} = \{\mathbb{V} > \mathcal{M}\mathbb{V}\} \quad \text{and} \quad \mathcal{I} = \{\mathbb{V} = \mathcal{M}\mathbb{V}\}.$$

is admissible and optimal.

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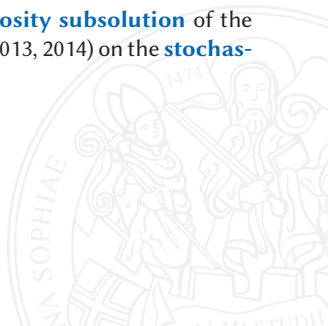
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- (4) By **viscosity comparison**: $\mathbb{V} \leq \mathbb{V}_*$, i.e. \mathbb{V} is continuous and the unique viscosity solution of the QVIs.

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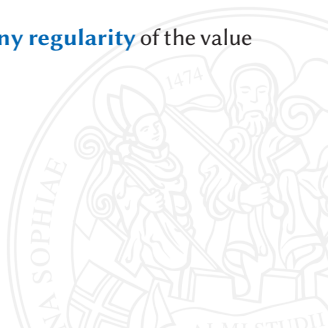
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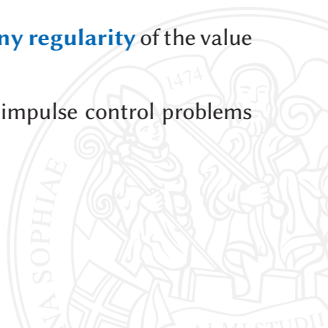
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- It allows us to verify optimality of controls **without any regularity** of the value function beyond **continuity**.
- The approach **generalizes** to a big class of general impulse control problems (see Belak, Christensen, and Seifried (2017)).



Thanks for your attention!

Belak and Christensen (2016):

Utility Maximization in a Factor Model with Constant and Proportional Costs

Belak, Christensen, and Seifried (2017):

A General Verification Result for Stochastic Impulse Control Problems

SIAM J. Control Optim., Vol. 55, No. 2, pp. 627–649

Available at: www.belak.ch/publications/

