

# Optimal Investment: Transaction Costs and Crash Threats

Christoph Belak

Stochastic Control and Financial Mathematics Group  
Department of Mathematics  
Kaiserslautern University of Technology

**Supervisor:**  
Prof. Dr. Jörn Saß  
TU Kaiserslautern

**Co-Supervisor:**  
Dr. Olaf Menkens  
Dublin City University

February 18, 2011

# Overview

- 1 Introduction: Merton's Optimal Investment Problem
- 2 Including Transaction Costs in the Model
- 3 Including Crash Scenarios in the Model

## Market Model: The Black-Scholes Market

We consider a **financial market** consisting of two tradable assets:

- 1 A **risk-free asset** (bond or bank account) with dynamics

$$dB_t = rB_t dt.$$

- 2 A **risk-bearing asset** (stock) with dynamics

$$dS_t = \alpha S_t dt + \sigma S_t dW_t.$$

The **total wealth**  $X_t$  of an investor then evolves according to

$$dX_t = (1 - \eta_t)X_t r dt + \eta_t X_t (\alpha dt + \sigma dW_t), \quad X_0 = 1,$$

where  $\eta_t$  denotes the fraction of the total wealth invested in the risky asset at time  $t$ , the so-called **risky-fraction process**.

# The Optimal Investment Problem

The objective is to find an investment strategy  $\eta_t^*$  which yields the highest **expected utility of the total wealth** at some terminal time  $T$ . That is, we face the problem

$$\sup_{\eta_t \in \mathcal{A}} E [U_p (X_T)].$$

We assume that  $U_p$  is a **utility function** of the form

$$U_p(x) = \begin{cases} \frac{1}{p} x^p & \text{if } p < 1, p \neq 0, \\ \log x & \text{if } p = 0. \end{cases}$$

The problem was solved in 1969 by Robert C. **Merton**.

## The Log-Utility Case

We consider the log-utility case  $U_0(x) = \log x$ . The wealth process

$$dX_t = (1 - \eta_t)X_t r dt + \eta_t X_t (\alpha dt + \sigma dW_t), \quad X_0 = 1,$$

can be written as

$$X_t = \exp \left\{ \int_0^t (1 - \eta_u) r + \eta_u \alpha - \frac{1}{2} \sigma^2 \eta_u^2 du + \int_0^t \sigma \eta_u dW_u \right\}.$$

Thus the problem reduces to

$$\sup_{\eta_t} E [U_0 (X_T)] = \sup_{\eta_t} E \left[ \int_0^T (1 - \eta_u) r + \eta_u \alpha - \frac{1}{2} \sigma^2 \eta_u^2 du \right].$$

Pointwise optimization yields

$$\eta_t^* = \frac{\alpha - r}{\sigma^2}.$$

**“Merton Fraction”**

# Shortcomings of the Merton Model

The model suggested by Merton has certain **shortcomings**.  
Possible extensions are:

- 1 The optimal solution in the Merton model requires the investor to continuously adjust his stock and bond positions. This does not work in practice, since transactions are usually subject to a fee.  
⇒ Include **transaction costs** into the model.
- 2 The stock price process is modelled as a continuous geometric Brownian motion which cannot describe extreme price movements.  
⇒ Include **crash scenarios** into the model.

# Including Transaction Costs in the Model

- 1 Introduction: Merton's Optimal Investment Problem
- 2 Including Transaction Costs in the Model**
- 3 Including Crash Scenarios in the Model

## Different Types of Transaction Costs

In the literature, one typically distinguishes between three different types of transaction costs:

- 1 **Constant Costs:** Pay constant  $C$  units of money per transaction.
- 2 **Fixed Costs:** Pay  $c \cdot X_t$  for some fraction  $c$  of the total wealth at time  $t$ .
- 3 **Proportional Costs:** Pay  $\gamma \cdot |\Delta|$  for some constant  $\gamma$  and transaction size  $\Delta$ .

Constant and fixed costs punish the **frequency of trading** whereas proportional costs punish the **size of the transaction**.



# The Market with Proportional Transaction Costs

Proportional Transaction Costs Models:

Davis/Norman (1990), Shreve/Soner (1994) and Day/Yi (2009).

## Bond and Stock Dynamics

The amounts of money invested in bond and stock follow

$$dB_t = rB_t dt$$

$$dS_t = \alpha S_t dt + \sigma S_t dW_t$$

# The Market with Proportional Transaction Costs

Proportional Transaction Costs Models:

Davis/Norman (1990), Shreve/Soner (1994) and Day/Yi (2009).

## Bond and Stock Dynamics

The amounts of money invested in bond and stock follow

$$dB_t = rB_t dt - (1 + \lambda) dL_t$$

$$dS_t = \alpha S_t dt + \sigma S_t dW_t + dL_t$$

$L_t$ : adapted, increasing, cadlag process representing the cumulative amount of money used for buying stock.

$\lambda \in (0, \infty)$  : transaction costs for buying

# The Market with Proportional Transaction Costs

Proportional Transaction Costs Models:

Davis/Norman (1990), Shreve/Soner (1994) and Day/Yi (2009).

## Bond and Stock Dynamics

The amounts of money invested in bond and stock follow

$$dB_t = rB_t dt - (1 + \lambda) dL_t + (1 - \mu) dM_t,$$

$$dS_t = \alpha S_t dt + \sigma S_t dW_t + dL_t - dM_t.$$

$L_t$ : adapted, increasing, cadlag process representing the cumulative amount of money used for buying stock.

$M_t$ : adapted, increasing, cadlag process representing the cumulative amount of money obtained from selling stock.

$\lambda \in (0, \infty)$ ,  $\mu \in (0, 1)$ : transaction costs for buying and selling.

## Admissible Trading Strategies

**Problem:** At terminal time  $T$ , what to do with the stock position?

$$X_t = \begin{cases} B_t + (1 - \mu)S_t & \text{if } S_t \geq 0, \\ B_t + (1 + \lambda)S_t & \text{if } S_t < 0. \end{cases} \quad \text{vs.} \quad X_t = B_t + S_t.$$

This inspires the definition of the following **solvency region**:

$$\mathcal{S} := \{(b, s) \in \mathbb{R}^2 : b + (1 + \lambda)s > 0, b + (1 - \mu)s > 0\}$$

The set of **admissible strategies** is then given by

$$\mathcal{A}(t, b, s) = \{(L, M) : X_u^{L, M} \in \bar{\mathcal{S}} \text{ for all } u \in [t, T]\}.$$

## Problem Formulation

For initial positions  $(b, s) \in \bar{\mathcal{S}}$ , the **optimal terminal wealth** problem then reads

$$\sup_{(L, M) \in \mathcal{A}(0, b, s)} E \left[ U_p \left( X_T^{L, M} \right) \middle| B_0 = b, S_0 = s \right].$$

For  $(t, b, s) \in [0, T) \times \bar{\mathcal{S}}$ , we define the **value function** to be

$$V(t, b, s) = \sup_{(L, M) \in \mathcal{A}(t, b, s)} E \left[ U_p \left( X_T^{L, M} \right) \middle| B_t = b, S_t = s \right].$$

If we want to be able to solve the optimization problem we need to assume that the value function is **finite**.

## Dynamic Programming and the HJB-equation

In order to solve the portfolio problem, we use the theory of **stochastic optimal control**. One needs the so-called **dynamic programming principle** which states

$$V(t, b, s) = \sup_{(L, M)} E [V(\tau, B_\tau, S_\tau) | B_t = b, S_t = s].$$

for every stopping time  $\tau$  taking values in  $[t, T)$ . This can be used to show that the value function is the unique solution to the partial differential equation (**HJB-equation**)

$$0 = \min \left\{ -V_t - \alpha s V_s - r b V_b - \frac{1}{2} s^2 \sigma^2 V_{ss}, \right. \\ \left. - (1 - \mu) V_b + V_s, (1 + \lambda) V_b - V_s \right\}.$$

# How to make these arguments rigorous?

How can we make these arguments rigorous?

- 1 Show that the value function satisfies the HJB-equation in a weak sense (**viscosity solution**).
- 2 Proof that the value function is sufficiently regular. This implies that the value function is also a **classical solution** of the HJB-equation.
- 3 Show that the optimal risky fraction process is a **diffusion process reflected at the boundaries** of  $\mathcal{R}_t^{buy}$  and  $\mathcal{R}_t^{sell}$ .

Especially the regularity is hard to obtain.

## A parabolic double obstacle problem

One can show that the HJB-equation is equivalent to the following **parabolic double obstacle problem**:

$$\begin{cases} -v_t - \mathcal{L}v = 0 & \text{if } \frac{1}{x+1+\lambda} < v(x, t) < \frac{1}{x+1-\mu} \\ -v_t - \mathcal{L}v \geq 0 & \text{if } v(x, t) = \frac{1}{x+1+\lambda} \\ -v_t - \mathcal{L}v \leq 0 & \text{if } v(x, t) = \frac{1}{x+1-\mu} \\ v(x, T) = \frac{1}{x+1-\mu} \end{cases}$$

for some differential operator  $\mathcal{L}$ .



# Including Crash Scenarios in the Model

- 1 Introduction: Merton's Optimal Investment Problem
- 2 Including Transaction Costs in the Model
- 3 Including Crash Scenarios in the Model**

# Modelling Crashes of the Stock

There are different approaches to **modelling stock crashes**. E.g.

- 1 Replace the Brownian motion which drives the stock price with a **Lévy process**.  
⇒ Jump intensities are hard to estimate in practice.
- 2 Model the crash process as a **control variable** held by the market and optimize over all worst-case scenarios.  
⇒ Stochastic game between investor and market.

In the sequel, we will take a look at the second approach.

# The Crash Market Model

Worst-Case Optimization:

Korn/Willmott (2002), Menkens (2004), Korn/Steffensen (2006),  
Seifried (2010).

## Bond and Stock Dynamics

The amounts of money invested in bond and stock follow

$$dB_t = rB_t dt - (1 + \lambda) dL_t + (1 - \mu) dM_t,$$

$$dS_t = \alpha S_t dt + \sigma S_t dW_t + dL_t - dM_t$$

# The Crash Market Model

Worst-Case Optimization:

Korn/Willmott (2002), Menkens (2004), Korn/Steffensen (2006), Seifried (2010).

## Bond and Stock Dynamics

The amounts of money invested in bond and stock follow

$$dB_t = rB_t dt - (1 + \lambda) dL_t + (1 - \mu) dM_t,$$

$$dS_t = \alpha S_t dt + \sigma S_t dW_t + dL_t - dM_t - \beta S_t dN_t.$$

$N_t$ : Crash process counting the number of crashes.

$\beta \in (0, 1)$ : crash height.

# The Crash Process

**Properties** of the crash process  $N_t$ :

- 1  $N_t$  **counts the number of crashes** up to time  $t$ .
- 2 We do not assume any distribution of the process. Instead, regard  $N_t$  as a control variable held by the market used to **minimize the total wealth** of the investor.
- 3 Thus, the problem can be regarded as a **game between the investor and the market**: The investor wants to find a strategy  $(L_t, M_t)$  in order to maximize expected utility of terminal wealth. The market wants to find a strategy  $N_t$  which minimizes this quantity.
- 4 We consider a finite horizon problem on  $[0, T]$  and **limit the maximal number of crashes** in this interval to  $N_{max}$ .

## Problem Formulation

The **optimization problem** in this model reads as follows

$$\sup_{(L,M)} \inf_N E \left[ U_p \left( X_T^{L,M,N} \right) \mid B_0 = b, S_0 = s \right].$$

The **value functions** in this case are given by

$$V^n(t, b, s) = \sup_{(L,M)} \inf_N E_{t,b,s,n} \left[ U_p \left( X_T^{L,M,N} \right) \right].$$

Here  $E_{t,b,s,n}$  denotes the conditional expectation given  $B_t = b$ ,  $S_t = s$  and that there are at most  $n$  crashes left.

## Characterization of the Value Function

We have a result similar to the dynamic programming principle.

### Theorem

The value function satisfies

$$\begin{aligned} V^n(t, b, s) &= \sup_{(L, M)} \inf_N E_{t, b, s, n} \left[ U \left( X_T^{L, M, N} \right) \right] \\ &= \sup_{(L, M)} \inf_{\tau} E_{t, b, s, n} \left[ V^{n-1} \left( \tau, \hat{B}_{\tau}, \hat{S}_{\tau} \right) \right], \end{aligned}$$

where

$$\begin{aligned} \hat{B}_t &= B_{t-} - (1 + \lambda)(L_t - L_{t-}) + (1 - \mu)(M_t - M_{t-}), \\ \hat{S}_t &= (1 - \beta)S_{t-} + (L_t - L_{t-}) - (M_t - M_{t-}). \end{aligned}$$

# Optimal Crash Time

The last theorem already allows us to deduce the **optimal crash strategy**.

## Theorem

Assume that at time  $t$  the market has  $n$  crash options left. Then the optimal crash time  $\tau_n^*$  is given by

$$\tau_n^* = \inf \left\{ u \geq t : V^n(u, B_u, S_u) \geq V^{n-1}(u, \hat{B}_u, \hat{S}_u) \right\}.$$



## Optimal Trading with Crashes

In a crash-threatened market one can show, that in between crash times **the HJB-equation still holds**. However, we obtain an additional constraint to become **indifferent about crashes**.

### Theorem

The value function satisfies the HJB equation

$$0 = \min \left\{ -V_t^n - \alpha s V_s^n - r b V_b^n - \frac{1}{2} \sigma^2 s^2 V_{ss}^n, \right. \\ \left. - (1 - \mu) V_b^n + V_s^n, (1 + \lambda) V_b^n - V_s^n \right\}$$

under the constraint

$$V^n(t, b, s) \leq V^{n-1}(t, b, (1 - \beta)s).$$



Any Questions??

Thank you for your attention!!